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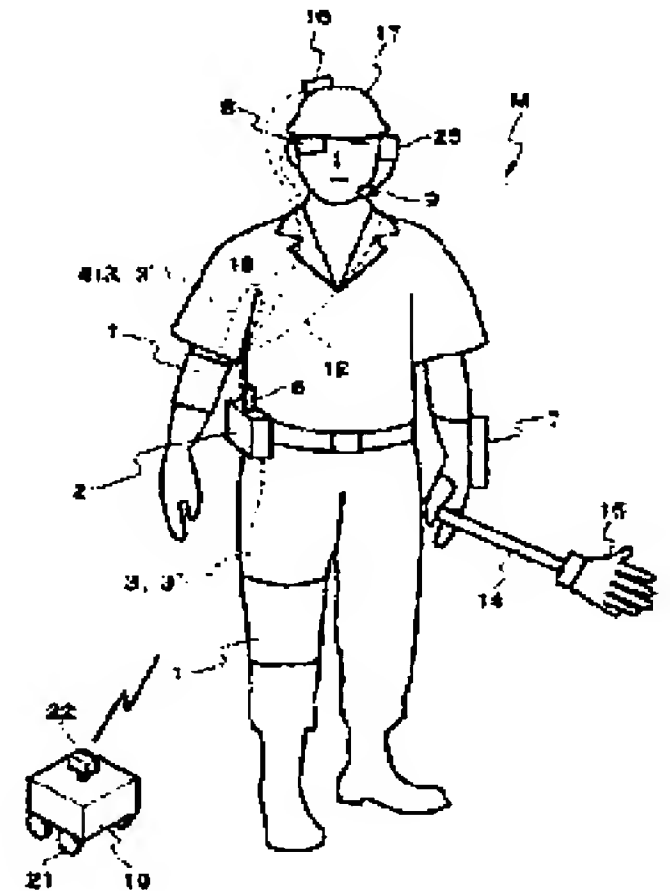
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(54) MAN-MACHINE ROBOT AND CONTROL METHOD OF MAN MACHINE ROBOT

(57)Abstract:

PROBLEM TO BE SOLVED: To provide a method of integrally cooperative control of a man and a machine.

SOLUTION: This control method is furnished with: an actuator 1 installed on a first installing part of a man body M and to give kinetic power to the first installing part; and a controller 2 installed on a second installing part of the man body M to control the kinetic power. The controller 2 and the actuator 1 are installed on the human body on which the controller 2 and the actuator 1 are physically integrated with the same person, and the man totally or partially acquires auxiliary kinetic power while moving together with the controller 2 and the actuator 1, and the integrally cooperative control of the man and the machine is realized.























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